

Announcements

Tuesday, February 13

Good job on the midterm!!

- ▶ This week is a review from MATH 1553
- ▶ Comprehensive notes can be found in <http://people.math.gatech.edu/~leslava3/1718S-2802.html>
- ▶ Selected material at <http://people.math.gatech.edu/~leslava3/1718S-2802/schedule.html>

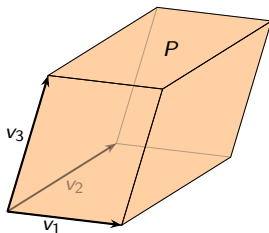
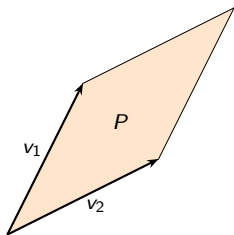
Sections 3.1-3.2

Determinants

The Idea of Determinants

Let A be an $n \times n$ matrix. **Determinants are only for square matrices.**

The columns v_1, v_2, \dots, v_n give you n vectors in \mathbf{R}^n . These determine a **parallelepiped** P .



Observation: the volume of P is zero \iff the columns are *linearly dependent* (P is “flat”) \iff the matrix A is not invertible.

The **determinant** of A will be a number $\det(A)$ whose absolute value is the *volume of P* .

In particular, $\det(A) \neq 0 \iff A$ is invertible.

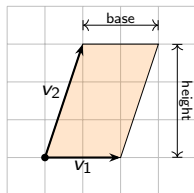
Determinants of 2×2 Matrices

Revisited

There is a formula in the 2×2 case:

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc.$$

What does this have to do with volumes?



$$v_1 = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

The area of the parallelogram is

$$\text{base} \times \text{height} = 2 \cdot 3 = \left| \det \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix} \right|.$$

The area of the parallelogram is always $|ad - bc|$. If v_1 is not on the x -axis: it's a fun geometry problem!

Note: The volume is zero if and only if the columns are collinear

Determinants of 3×3 Matrices

Here's a formula:

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}$$

How to remember this?

Draw a bigger matrix, repeating the first two columns to the right:

$$+ \begin{vmatrix} a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{vmatrix} - \begin{vmatrix} a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{vmatrix}$$

For example,

$$\det \begin{pmatrix} 5 & 1 & 0 \\ -1 & 3 & 2 \\ 4 & 0 & -1 \end{pmatrix} = \begin{vmatrix} 5 & 1 & 0 & 5 & 1 \\ -1 & 3 & 2 & -1 & 3 \\ 4 & 0 & -1 & 4 & 0 \end{vmatrix} = -15 + 8 + 0 - 0 - 0 - 1 = -8$$

Cofactor expansion

Recursive formula: you compute a larger determinant *in terms of smaller ones*.

Let A be an $n \times n$ matrix.

A_{ij} = ij th **minor** of A

= $(n - 1) \times (n - 1)$ matrix you get by *deleting the i th row and j th column*

C_{ij} = ij th **cofactor** of $A = (-1)^{i+j} \det A_{ij}$

The signs of the cofactors follow a *checkerboard pattern*:

$$\begin{pmatrix} + & - & + & - \\ - & + & - & + \\ + & - & + & - \\ - & + & - & + \end{pmatrix} \quad \pm \text{ in the } ij \text{ entry is the sign of } C_{ij}$$

Definition

The **determinant** of an $n \times n$ matrix A is

$$\det(A) = \sum_{j=1}^n a_{1j} C_{1j} = a_{11} C_{11} + a_{12} C_{12} + \cdots + a_{1n} C_{1n}.$$

This formula is called **cofactor expansion** *along the first row*.

Example: Cofactor expansion along first row

$$\begin{aligned} \det \begin{pmatrix} 5 & 1 & 0 \\ -1 & 3 & 2 \\ 4 & 0 & -1 \end{pmatrix} &= 5 \cdot \det \begin{pmatrix} \color{green}{5} & \color{red}{1} & \color{red}{0} \\ \color{red}{-1} & -3 & 2 \\ \color{red}{4} & 0 & -1 \end{pmatrix} - 1 \cdot \det \begin{pmatrix} \color{red}{5} & \color{green}{1} & \color{red}{0} \\ -1 & \color{red}{3} & 2 \\ 4 & \color{red}{0} & -1 \end{pmatrix} \\ &\quad + 0 \cdot \det \begin{pmatrix} \color{red}{5} & \color{red}{1} & \color{green}{0} \\ -1 & 3 & \color{red}{2} \\ 4 & 0 & \color{red}{-1} \end{pmatrix} \\ &= 5 \cdot \det \begin{pmatrix} 3 & 2 \\ 0 & -1 \end{pmatrix} - 1 \cdot \det \begin{pmatrix} -1 & 2 \\ 4 & -1 \end{pmatrix} + 0 \cdot \det \begin{pmatrix} -1 & 3 \\ 4 & 0 \end{pmatrix} \\ &= 5 \cdot (-3 - 0) - 1 \cdot (1 - 8) \\ &= -15 + 7 = -8 \end{aligned}$$

Cofactor expansion: Specify point of reference...

Recall: the cofactor expansion *along the first row*.

$$\det(A) = \sum_{j=1}^n a_{1j} C_{1j} = a_{11} C_{11} + a_{12} C_{12} + \cdots + a_{1n} C_{1n}.$$

Actually, you can expand cofactors along any **row** or **column** you like! **Good**

trick: Use cofactor expansion along a row or a column *with a lot of zeros*.

$$A = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 5 & 9 & 1 \end{pmatrix}$$

It looks easiest to expand along the third column:

$$\begin{aligned} \det A &= 0 \cdot \det \begin{pmatrix} \text{don't} \\ \text{care} \end{pmatrix} - 0 \cdot \det \begin{pmatrix} \text{don't} \\ \text{care} \end{pmatrix} + 1 \cdot \det \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 5 & 9 & 1 \end{pmatrix} \\ &= \det \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} = 2 - 1 = 1 \end{aligned}$$

Poll

$$\det \begin{pmatrix} 1 & 7 & -5 & 14 & 3 & 22 \\ 0 & -2 & -3 & 13 & 11 & 1 \\ 0 & 0 & -1 & -9 & 7 & 18 \\ 0 & 0 & 0 & 3 & 6 & -8 \\ 0 & 0 & 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix} = ?$$

A. -6 B. -3 C. -2 D. -1 E. 1 F. 2 G. 3 H. 6

If you *expand repeatedly along the first column*, you get

$$\begin{aligned} 1 \cdot \det \begin{pmatrix} -2 & -3 & 13 & 11 & 1 \\ 0 & -1 & -9 & 7 & 18 \\ 0 & 0 & 3 & 6 & -8 \\ 0 & 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 0 & -1 \end{pmatrix} &= 1 \cdot (-2) \cdot \det \begin{pmatrix} -1 & -9 & 7 & -18 \\ 0 & 3 & 6 & -8 \\ 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= 1 \cdot (-2) \cdot (-1) \cdot \det \begin{pmatrix} 3 & 6 & -8 \\ 0 & 1 & -11 \\ 0 & 0 & -1 \end{pmatrix} = 1 \cdot (-2) \cdot (-1) \cdot 3 \cdot \det \begin{pmatrix} 1 & -11 \\ 0 & -1 \end{pmatrix} \\ &= 1 \cdot (-2) \cdot (-1) \cdot 3 \cdot 1 \cdot (-1) = -6 \end{aligned}$$

The Determinant of an Upper-Triangular Matrix

Theorem

The determinant of an upper-triangular matrix is the product of the diagonal entries:

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ 0 & a_{22} & a_{23} & \cdots & a_{2n} \\ 0 & 0 & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{pmatrix} = a_{11} a_{22} a_{33} \cdots a_{nn}.$$

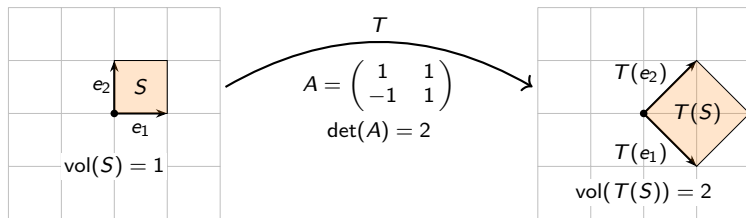
Trick: Expand along the last row

This works for any matrix that is *upper-triangular* (all entries below the main diagonal are zero).

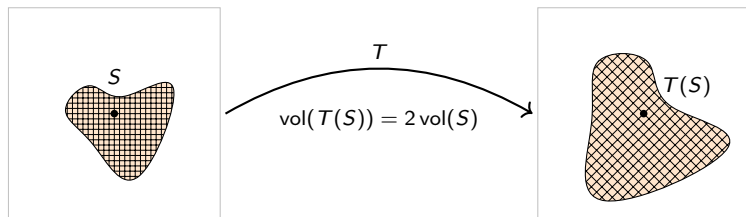
The same is true for lower-triangular matrices. (Repeatedly expand along the first row.)

Linear Transformations and volumen

If S is the *unit cube*, then $T(S)$ is the parallelepiped formed by the columns of A . The **volumen changes** according to $\det(A)$.



For curvy regions: break S up into *tiny cubes*; each one is scaled by $|\det(A)|$. Then use *calculus* to reduce to the previous situation!



Defining the Determinant in Terms of its Properties

Definition

The **determinant** is a function

$$\det: \{\text{square matrices}\} \longrightarrow \mathbf{R}$$

with the following defining properties:

1. $\det(I_n) = 1$
2. If we do a *row replacement* on a matrix, the determinant does not change.
3. If we *swap* two rows of a matrix, the determinant scales by -1 .
4. If we *scale a row* of a matrix by k , the determinant scales by k .

Why would we think of these properties? This is how volumes work!

1. The volume of the *unit cube* is 1.
2. Volumes don't change under *a shear*.
3. Volume of a *mirror image* is negative of the volume?
4. If you *scale one coordinate* by k , the volume is multiplied by k .

Properties of the Determinant

2×2 matrix

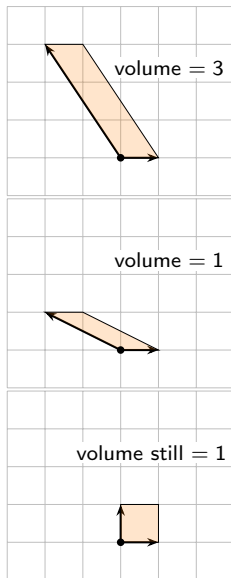
$$\det \begin{pmatrix} 1 & -2 \\ 0 & 3 \end{pmatrix} = 3$$

Scale: $R_2 = \frac{1}{3}R_2$

$$\det \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} = 1$$

Row replacement: $R_1 = R_1 + 2R_2$

$$\det \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1$$



Magical Properties of the Determinant

you really have to know these

1. $\det: \{\text{square matrices}\} \rightarrow \mathbf{R}$ is *the only function* satisfying the defining properties (1)–(4).

2. A is *invertible* if and only if $\det(A) \neq 0$.

3. If we row reduce A *without row scaling*, then

$$\det(A) = (-1)^{\#\text{swaps}} (\text{product of diagonal entries in REF}).$$

4. The determinant can be computed using any *cofactor expansion*.

5. $\det(AB) = \det(A)\det(B)$ and $\det(A^{-1}) = \det(A)^{-1}$.

6. $\det(A) = \det(A^T)$.

7. $|\det(A)|$ is the volume of the *parallelepiped* defined by the columns of A .

8. If A is an $n \times n$ matrix with transformation $T(x) = Ax$, and S is a subset of \mathbf{R}^n , then the *volume of $T(S)$* is $|\det(A)|$ times the volume of S . (Even for curvy shapes S .)

9. The determinant is *multi-linear* (optional material).

Computing the Determinant by Row Reduction

Example first

We can use the properties of the determinant and row reduction to compute the determinant of any matrix!

$$\det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 5 & 7 & -4 \end{pmatrix} = -\det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 5 & 7 & -4 \end{pmatrix} \quad (\text{swap})$$

$$= -\det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 7 & -9 \end{pmatrix} \quad (\text{'shear'})$$

$$= -\det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -9 \end{pmatrix} \quad (\text{'shear'})$$

The **second matrix** is obtained from the **first matrix** by scaling by $-1/9$. So the determinant of the **first matrix** is -9 times the determinant of the **second matrix**.

$$= (-1) \cdot (-9) \det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (\text{scale})$$

$$= (-1) \cdot (-9) \det \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (\text{'shear'})$$

$$= 9 \quad (\text{cube})$$

Computing the Determinant by Row Reduction

Saving some work We can stop row reducing when we get to row echelon form.

$$\det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 5 & 7 & -4 \end{pmatrix} = \dots = -\det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -9 \end{pmatrix} = 9.$$

Row reduction

This is almost always the easiest way to compute the determinant of a large, complicated matrix, either by hand or by computer.

Cofactor expansion is $O(n!) \sim O(n^n \sqrt{n})$, row reduction is $O(n^3)$.

Extra: Multi-Linearity of the Determinant

Think of \det as a function of the *columns* of an $n \times n$ matrix:

$$\det: \underbrace{\mathbf{R}^n \times \mathbf{R}^n \times \cdots \times \mathbf{R}^n}_{n \text{ times}} \longrightarrow \mathbf{R}$$

$$\det(v_1, v_2, \dots, v_n) = \det \left(\begin{array}{c|c|c|c} | & | & \cdots & | \\ v_1 & v_2 & & v_n \\ | & | & & | \end{array} \right).$$

Multi-linear: For *any* i and any vectors v_1, v_2, \dots, v_n and v'_i and any scalar c ,

$$\det(v_1, \dots, v_i + v'_i, \dots, v_n) = \det(v_1, \dots, v_i, \dots, v_n) + \det(v_1, \dots, v'_i, \dots, v_n)$$

$$\det(v_1, \dots, cv_i, \dots, v_n) = c \det(v_1, \dots, v_i, \dots, v_n).$$

In words: if column i is a sum of two vectors v_i, v'_i , then the determinant is the sum of two determinants, one with v_i in column i , and one with v'_i in column i .

Proof: just expand cofactors along column i .

- ▶ We already knew: Scaling *one column* by c scales \det by c .
- ▶ *Same properties* hold if we replace column *by row*.
- ▶ *This only works one column (or row) at a time.*

Extra: The Determinant is a Function

We can think of the *determinant as a function* of the entries of a matrix:

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} \\ - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}.$$

The formula for the determinant of an $n \times n$ matrix has $n!$ terms.

When mathematicians encounter a function whose *formula is too difficult* to write down, we try to **characterize it in terms of its properties**.

P characterizes object X

Not only does object X have property P ,
but **X is the only one** thing that has property P .

Other example:

- ▶ e^x is unique function that has $f'(x) = f(x)$ and $f(0) = 1$.

Extra: Why is Property 5 true?

In Lay, there's a proof using elementary matrices. Here's another one.

Let B be an $n \times n$ matrix. There are two cases:

1. If $\det(B) = 0$, then B is not invertible. So for any matrix A , BA is not invertible. (Otherwise $B^{-1} = A(BA)^{-1}$.) So

$$\det(BA) = 0 = 0 \cdot \det(A) = \det(B) \det(A).$$

2. If A is invertible, define another function

$$f: \{n \times n \text{ matrices}\} \longrightarrow \mathbf{R} \quad \text{by} \quad f(B) = \frac{\det(BA)}{\det(A)}.$$

Let's check the defining properties:

1. $f(I_n) = \det(I_n A) / \det(A) = 1$.
- 2–4. Doing a row operation on B and then multiplying by A , does the *same row operation* on BA . This is because a row operation is left-multiplication by an elementary matrix E , and $(EB)A = E(BA)$. Hence f scales like \det with respect to row operations.

By uniqueness, $f = \det$, i.e.,

$$\det(B) = f(B) = \frac{\det(AB)}{\det(A)} \quad \text{so} \quad \det(A) \det(B) = \det(AB).$$