

# Announcements

Monday, September 18

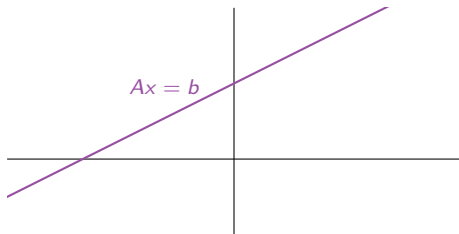
- ▶ **Midterm makeup exam:** Monday, September 25, from 5:00-5:50 PM in Skiles 005
- ▶ **Review session in this room:** Wednesday 20th, 5-6pm
  - ▶ 10min for general advice and to list down common questions to review (I will need your participation)
  - ▶ 30 min to review definition of echelon forms, Span, and parametrized vector solutions
  - ▶ 20 min to review your questions

# Section 1.5

## Solution Sets of Linear Systems

## Plan For Today

*Describe and draw* the solution set of  $Ax = b$ , using spans and parametric vector solutions.



**Recall:** the **solution set** is the collection of all vectors  $x$  such that  $Ax = b$  is true.

## Example 1

### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & 3 & 4 \\ 2 & -1 & 2 \\ 1 & 0 & 1 \end{pmatrix}?$$

We know how to do this: first form an augmented matrix and row reduce.

$$\left( \begin{array}{ccc|c} 1 & 3 & 4 & 0 \\ 2 & -1 & 2 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right) \xrightarrow{\text{row reduce}} \left( \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right).$$

The only solution is the trivial solution  $x = 0$ .

#### Observation

Since the last column (*everything to the right of the =*) was zero to begin, it will always *stay zero!*

For these cases it's not necessary to write augmented matrices.

## Example 2, explained

### Question

What is the solution set of  $Ax = b$ , where

$$A = \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} -3 \\ -6 \end{pmatrix}?$$

$$\left( \begin{array}{cc|c} 1 & -3 & -3 \\ 2 & -6 & -6 \end{array} \right) \xrightarrow{\text{row reduce}} \left( \begin{array}{cc|c} 1 & -3 & -3 \\ 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\text{equation}} x_1 - 3x_2 = -3$$

$$\xrightarrow{\text{parametric form}} \begin{cases} x_1 = 3x_2 - 3 \\ x_2 = x_2 + 0 \end{cases}$$

$$\xrightarrow{\text{parametric vector form}} x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix} + \begin{pmatrix} -3 \\ 0 \end{pmatrix}.$$

**Note** that  $p$  is itself a solution: take  $x_2 = 0$ .

## Example 3, explained

### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix}?$$

$$\begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \xrightarrow{\text{row reduce}} \begin{pmatrix} 1 & -3 \\ 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\text{equation}} x_1 - 3x_2 = 0$$

$$\xrightarrow{\text{parametric form}} \begin{cases} x_1 = 3x_2 \\ x_2 = x_2 \end{cases}$$

$$\xrightarrow{\text{parametric vector form}} x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix}.$$

## Parametric vector forms

These equations are called the **parametric vector form** of the solutions.

It is obtained by listing equations for all the variables, in order, including the free ones, and making a vector equation.

# Parametric Vector Form and Span

In general

Let  $A$  be an  $m \times n$  matrix. If the *free variables* in the equation  $Ax = b$  are  $x_i, x_j, x_k, \dots$

And the **parametric vector form** of the solution is

$$x = b' + x_i v_i + x_j v_j + x_k v_k + \dots$$

for some vectors  $b', v_i, v_j, v_k, \dots$  in  $\mathbf{R}^n$ , and any scalars  $x_i, x_j, x_k, \dots$

Then the solution set is

$$b' + \text{Span}\{v_i, v_j, v_k, \dots\}.$$



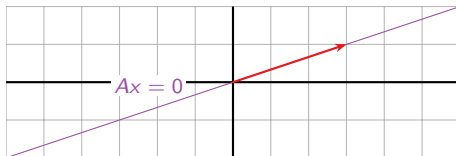
## Example 3, figure

### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix}?$$

**Answer:**  $x = x_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix}$  for any  $x_2$  in  $\mathbf{R}$ . The solution set is  $\text{Span}\left\{\begin{pmatrix} 3 \\ 1 \end{pmatrix}\right\}$ .



**Note:** *one* free variable means the solution set is a *line* in  $\mathbf{R}^2$  ( $2 = \#$  variables  $= \#$  columns).

## Example 2, with figure

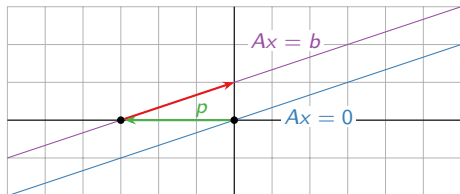
### Question

What is the solution set of  $Ax = b$ , where

$$A = \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} -3 \\ -6 \end{pmatrix}?$$

**Answer:**  $x = x_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix} + \begin{pmatrix} -3 \\ 0 \end{pmatrix}$  for any  $x_2$  in  $\mathbf{R}$ .

This is a *translate* of  $\text{Span}\left\{\begin{pmatrix} 3 \\ 1 \end{pmatrix}\right\}$ : it is the parallel line through  $p = \begin{pmatrix} -3 \\ 0 \end{pmatrix}$ .



It can be written

$$\text{Span}\left\{\begin{pmatrix} 3 \\ 1 \end{pmatrix}\right\} + \begin{pmatrix} -3 \\ 0 \end{pmatrix}.$$

# Parametric vector form

## Example 4, explained

### Question

What is the solution set of  $Ax = 0$ , where  $A =$

$$\begin{pmatrix} 1 & 2 & 0 & -1 \\ -2 & -3 & 4 & 5 \\ 2 & 4 & 0 & -2 \end{pmatrix} \xrightarrow{\text{row reduce}} \begin{pmatrix} 1 & 0 & -8 & -7 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\text{equations}} \begin{cases} x_1 - 8x_3 - 7x_4 = 0 \\ x_2 + 4x_3 + 3x_4 = 0 \end{cases}$$

$$\xrightarrow{\text{parametric form}} \begin{cases} x_1 = 8x_3 + 7x_4 \\ x_2 = -4x_3 - 3x_4 \\ x_3 = x_3 \\ x_4 = x_4 \end{cases}$$

$$\xrightarrow{\text{parametric vector form}} x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_3 \begin{pmatrix} 8 \\ -4 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 7 \\ -3 \\ 0 \\ 1 \end{pmatrix}.$$

# Parametric Vector form

## Example 4

### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & 2 & 0 & -1 \\ -2 & -3 & 4 & 5 \\ 2 & 4 & 0 & -2 \end{pmatrix}?$$

Answer:  $\text{Span} \left\{ \begin{pmatrix} 8 \\ -4 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 7 \\ -3 \\ 0 \\ 1 \end{pmatrix} \right\}.$

[not pictured here]

**Note:** *two* free variables means the solution set is a *plane* in  $\mathbf{R}^4$  ( $4 = \#$  variables  $= \#$  columns).

# Homogeneous Systems

Everything is easier when  $b = 0$ , so we start with this case.

## Definition

A system of linear equations of the form  $Ax = 0$  is called *homogeneous*.

A homogeneous system *always has the solution*  $x = 0$ . This is called the *trivial solution*. The nonzero solutions are called **nontrivial**.

### Observation

$Ax = 0$  has a *nontrivial* solution

$\iff$  there is a free variable

$\iff A$  has a *column with no pivot*.

**The opposite:**

## Definition

A system of linear equations of the form  $Ax = b$  with  $b \neq 0$  is called **nonhomogeneous** or **inhomogeneous**.

## Poll

How many solutions can there be to a homogeneous system with more equations than variables?

- A. 0
- B. 1
- C.  $\infty$

The trivial solution is always a solution to a homogeneous system, so answer A is impossible.

This matrix has only one solution to  $Ax = 0$ :

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$$

This matrix has infinitely many solutions to  $Ax = 0$ :

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

## Solutions for Homogeneous Systems

Let  $c$  be a scalar,  $u, v$  be vectors, and  $A$  a matrix.

►  $A(u + v) = Au + Av$

►  $A(cv) = cAv$

See Lay, §1.4, Theorem 5.

For instance,  $A(3u - 7v) = 3Au - 7Av$ .

**Consequence:** If  $u$  and  $v$  are solutions to  $Ax = 0$ , then so is every vector in  $\text{Span}\{u, v\}$ . Why?

$$\begin{cases} Au = 0 \\ Av = 0 \end{cases} \implies A(c_1u + c_2v) = c_1Au + c_2Av = c_10 + c_20 = 0.$$

(Here  $0$  means the zero vector.)

Important

The set of **solutions to  $Ax = 0$**  is **a span**.

## Solutions for **Consistent** Nonhomogeneous Systems

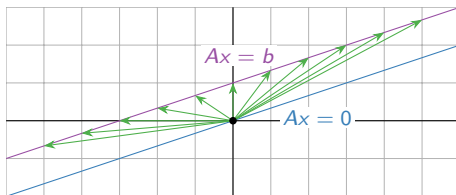
When consistent

The set of **solutions to**  $Ax = b$ , is **parallel** to a span.

**Why?** solutions are obtained by taking one **specific** or **particular solution**  $p$  to  $Ax = b$ , and *adding all solutions to*  $Ax = 0$ .

If  $Ap = b$  and  $Ax = 0$ , then  $p + x$  is also a solution to  $Ax = b$ :

$$A(p + x) = Ap + Ax = b + 0 = b.$$



**Note:**

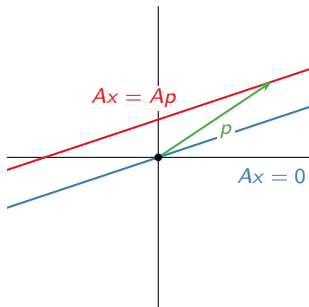
Works for *any specific solution*  $p$ : it doesn't matter how one found it!



## Reverse Engineering: Nonhomogeneous System

### Question

Give a system whose solution set **passes through point  $p$**  and it is **parallel to** the solution set of  $Ax = 0$ .



1. Set  $b = Ap$ .  
Entries in  $p$  are the weights that produce  $b$  as a linear combination of columns of  $A$ .
2. Now  $p$  is a specific solution to  $Ax = b$ ,
3. so  $Ax = b$  is the system we wanted.

**Take out:** If we describe the solution set of  $Ax = 0$ , then we can describe the solution set of  $Ax = b$  for all  $b$  in the *Span of columns of  $A$* .

## Extra: An homogeneous System

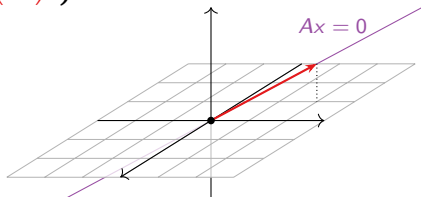
### Example 5

#### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & -1 & -5 \\ 1 & 0 & -2 \end{pmatrix}?$$

Answer:  $\text{Span} \left\{ \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \right\}.$



Note: *one* free variable means the solution set is a *line* in  $\mathbf{R}^3$  ( $3 = \#$  variables  $= \#$  columns).

## Extra: An homogeneous System

Example 5, explained

### Question

What is the solution set of  $Ax = 0$ , where

$$A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & -1 & -5 \\ 1 & 0 & -2 \end{pmatrix}?$$

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & -1 & -5 \\ 1 & 0 & -2 \end{pmatrix} \xrightarrow{\text{row reduce}} \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\text{equations}} \begin{cases} x_1 - 2x_3 = 0 \\ x_2 + x_3 = 0 \end{cases}$$

$$\xrightarrow{\text{parametric form}} \begin{cases} x_1 = 2x_3 \\ x_2 = -x_3 \\ x_3 = x_3 \end{cases}$$

$$\xrightarrow{\text{parametric vector form}} x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}.$$

## Extra: A Nonhomogeneous System

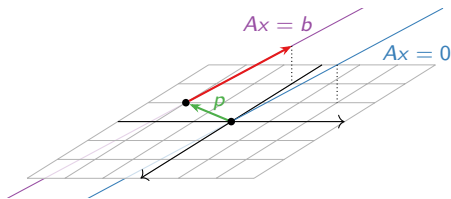
### Example 6

#### Question

What is the solution set of  $Ax = b$ , where

$$A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & -1 & -5 \\ 1 & 0 & -2 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} -5 \\ -3 \\ -2 \end{pmatrix}?$$

Answer:  $\text{Span} \left\{ \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \right\} + \begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix}.$



The solution set is a *translate* of

$$\text{Span} \left\{ \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \right\} :$$

it is the parallel line through

$$p = \begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix}.$$

## Extra: A Nonhomogeneous System

Example 6, explained

### Question

What is the solution set of  $Ax = b$ , where

$$A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & -1 & -5 \\ 1 & 0 & -2 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} -5 \\ -3 \\ -2 \end{pmatrix}?$$

$$\left( \begin{array}{ccc|c} 1 & 3 & 1 & -5 \\ 2 & -1 & -5 & -3 \\ 1 & 0 & -2 & -2 \end{array} \right) \xrightarrow{\text{row reduce}} \left( \begin{array}{ccc|c} 1 & 0 & -2 & -2 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\text{equations}} \begin{cases} x_1 - 2x_3 = -2 \\ x_2 + x_3 = -1 \end{cases}$$

$$\xrightarrow{\text{parametric form}} \begin{cases} x_1 = 2x_3 - 2 \\ x_2 = -x_3 - 1 \\ x_3 = x_3 \end{cases}$$

$$\xrightarrow{\text{parametric vector form}} x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + \begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix}.$$