

Section 3.2

Properties of Determinants

Plan for Today

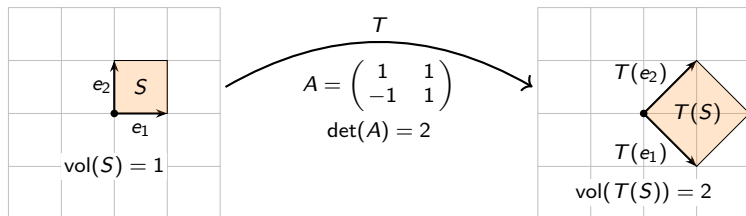
Last time, we gave a recursive formula for determinants in terms of cofactor expansions.

Plan for today:

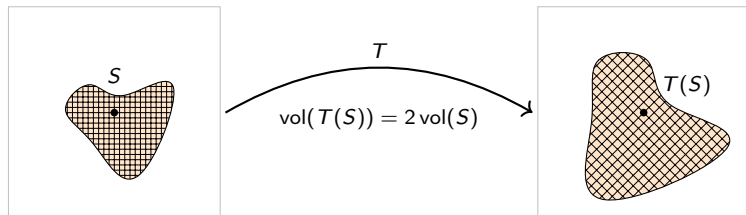
- ▶ An **abstract definition** of the determinant in terms of its properties.
- ▶ Computing determinants **using row operations**.
- ▶ Determinants and *products*: $\det(AB) = \det(A) \det(B)$,
- ▶ interpretation as volume,
- ▶ and linear transformations.

Linear Transformations and volumen

If S is the **unit cube**, then $T(S)$ is the parallelepiped formed by the columns of A . The **volumen changes** according to $\det(A)$.



For curvy regions: break S up into **tiny cubes**; each one is scaled by $|\det(A)|$. Then use **calculus** to reduce to the previous situation!



The Determinant is a Function

We can think of the *determinant as a function* of the entries of a matrix:

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = \begin{aligned} & a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} \\ & - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}. \end{aligned}$$

The formula for the determinant of an $n \times n$ matrix has $n!$ terms.

When mathematicians encounter a function whose *formula is too difficult* to write down, we try to **characterize it in terms of its properties**.

P characterizes object X

Not only does object X have property P ,
but **X is the only one** thing that has property P .

Other example:

- ▶ e^x is unique function that has $f'(x) = f(x)$ and $f(0) = 1$.

Defining the Determinant in Terms of its Properties

Definition

The **determinant** is a function

$$\det: \{\text{square matrices}\} \longrightarrow \mathbf{R}$$

with the following **defining properties**:

1. $\det(I_n) = 1$
2. If we do a *row replacement* on a matrix, the determinant does not change.
3. If we *swap* two rows of a matrix, the determinant scales by -1 .
4. If we *scale a row* of a matrix by k , the determinant scales by k .

Why would we think of these properties? This is how volumes work!

1. The volume of the *unit cube* is 1.
2. Volumes don't change under *a shear*.
3. Volume of a *mirror image* is negative of the volume?
4. If you *scale one coordinate* by k , the volume is multiplied by k .

Properties of the Determinant

2×2 matrix

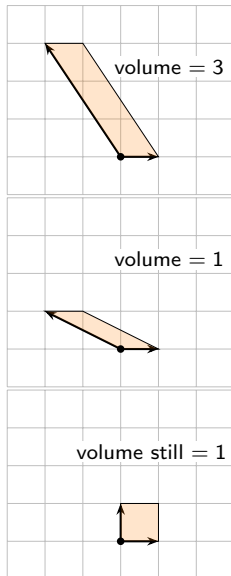
$$\det \begin{pmatrix} 1 & -2 \\ 0 & 3 \end{pmatrix} = 3$$

Scale: $R_2 = \frac{1}{3}R_2$

$$\det \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} = 1$$

Row replacement: $R_1 = R_1 + 2R_2$

$$\det \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1$$



Determinant for Elementary matrices

It is easy to calculate the determinant of an elementary matrix:

$$\det \begin{pmatrix} 1 & 0 & 8 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

$$\det \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} =$$

$$\det \begin{pmatrix} 1 & 0 & 0 \\ 0 & 17 & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

Computing the Determinant by Row Reduction

Example first

We can use the properties of the determinant and row reduction to compute the determinant of any matrix!

$$\det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 5 & 7 & -4 \end{pmatrix} =$$

Computing the Determinant by Row Reduction

We can use the properties of the determinant and row reduction to compute the determinant of any matrix!

Recall: The determinant of a *triangular matrix* is the product of the diagonal entries.

Saving some work We can stop row reducing when we get to row echelon form.

$$\det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 5 & 7 & -4 \end{pmatrix} = \cdots = -\det \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -9 \end{pmatrix} = 9.$$

Row reduction

This is almost always the easiest way to compute the determinant of a large, complicated matrix, either by hand or by computer.

Cofactor expansion is $O(n!) \sim O(n^n \sqrt{n})$, row reduction is $O(n^3)$.

Magical Properties of the Determinant

you really have to know these

1. $\det: \{\text{square matrices}\} \rightarrow \mathbf{R}$ is *the only function* satisfying the defining properties (1)–(4).

2. A is *invertible* if and only if $\det(A) \neq 0$.

3. If we row reduce A *without row scaling*, then

$$\det(A) = (-1)^{\# \text{swaps}} (\text{product of diagonal entries in REF}).$$

4. The determinant can be computed using any *cofactor expansion*.

5. $\det(AB) = \det(A)\det(B)$ and $\det(A^{-1}) = \det(A)^{-1}$.

6. $\det(A) = \det(A^T)$.

7. $|\det(A)|$ is the volume of the *parallelepiped* defined by the columns of A .

8. If A is an $n \times n$ matrix with transformation $T(x) = Ax$, and S is a subset of \mathbf{R}^n , then the *volume of $T(S)$* is $|\det(A)|$ times the volume of S . (Even for curvy shapes S .)

9. The determinant is *multi-linear* (we'll talk about this next).

Multi-Linearity of the Determinant

Think of **det** as a function of the **columns** of an $n \times n$ matrix:

$$\det: \underbrace{\mathbf{R}^n \times \mathbf{R}^n \times \cdots \times \mathbf{R}^n}_{n \text{ times}} \longrightarrow \mathbf{R}$$

$$\det(v_1, v_2, \dots, v_n) = \det \begin{pmatrix} | & | & \cdots & | \\ v_1 & v_2 & \cdots & v_n \\ | & | & \cdots & | \end{pmatrix}.$$

Multi-linear: For **any** i and any vectors v_1, v_2, \dots, v_n and v'_i and any scalar c ,

$$\det(v_1, \dots, v_i + v'_i, \dots, v_n) = \det(v_1, \dots, v_i, \dots, v_n) + \det(v_1, \dots, v'_i, \dots, v_n)$$

$$\det(v_1, \dots, cv_i, \dots, v_n) = c \det(v_1, \dots, v_i, \dots, v_n).$$

- ▶ We already knew: Scaling **one column** by c scales \det by c .
- ▶ *This only works one column at a time.*
- ▶ *Same properties* hold if we replace column **by row**.

Extra: Mathematical intricacies

The characterization of the determinant function in terms of its properties is very useful. It will *give us a fast way to compute* determinants and prove the other properties.

The **disadvantage** of defining a function by its properties *before having a formula*:

- ▶ how do you know such a *function exists*?
- ▶ *is there only one* function satisfying those properties?

Extra: Intricacy applied

Why is **Property 5** true? In Lay, there's a proof using elementary matrices. Here's another one.