Chapter 5

Eigenvalues and Eigenvectors

Section 5.1

Eigenvectors and Eigenvalues

Motivation: Difference equations

A Biology Question

How to predict a population of rabbits with given **dynamics**:

1. half of the newborn rabbits *survive* their first year;
2. of those, half *survive* their second year;
3. their maximum *life span* is three years;
4. Each rabbit gets $0, 6, 8$ *baby rabbits* in their three years, respectively.

Approach: Each year, count the population **by age**:

$$v_n = \begin{pmatrix} f_n \\ s_n \\ t_n \end{pmatrix} \text{ where } \begin{cases} f_n & = \text{first-year rabbits in year } n \\ s_n & = \text{second-year rabbits in year } n \\ t_n & = \text{third-year rabbits in year } n \end{cases}$$

The *dynamics say*:

$$\overbrace{\begin{pmatrix} f_{n+1} \\ s_{n+1} \\ t_{n+1} \end{pmatrix}}^{v_{n+1}} = \begin{pmatrix} 6s_n + 8t_n \\ f_n/2 \\ s_n/2 \end{pmatrix} = \overbrace{\begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} f_n \\ s_n \\ t_n \end{pmatrix}}^{Av_n}.$$

Motivation: Difference equations

Continued

This is a **difference equation**: $Av_n = v_{n+1}$

If you know *initial population* v_0, what happens *in 10 years* v_{10}?

Plug in a computer:

v_0	v_{10}	v_{11}
$\begin{pmatrix}1\\2\\3\end{pmatrix}$	$\begin{pmatrix}9459\\2434\\577\end{pmatrix}$	$\begin{pmatrix}19222\\4729\\1217\end{pmatrix}$
$\begin{pmatrix}3\\7\\9\end{pmatrix}$	$\begin{pmatrix}30189\\7761\\1844\end{pmatrix}$	$\begin{pmatrix}61316\\15095\\3881\end{pmatrix}$
$\begin{pmatrix}16\\4\\1\end{pmatrix}$	$\begin{pmatrix}16384\\4096\\1024\end{pmatrix}$	$\begin{pmatrix}32768\\8192\\2048\end{pmatrix}$

Notice any patterns?

1. Each segment of the population *essentially doubles* every year: $Av_{11} \approx 2v_{10}$.
2. The ratios get close to $(16 : 4 : 1)$:

$$v_{11} \approx (\text{big}\#) \cdot \begin{pmatrix}16\\4\\1\end{pmatrix}.$$

New terms coming: eigenvalue, and eigenvector

Motivation: Difference equations
Continued (2)

We *want a formula* for vectors $v_0, v_1, v_2, \ldots$, such that

$$Av_0 = v_1 \qquad Av_1 = v_2 \qquad Av_2 = v_3 \qquad \ldots$$

We can see that $v_n = A^n v_0$. But multiplying by A each time is inefficient!

If v_0 satisfies $A_{v_0} = \lambda v_0$ then

$$v_n = A^{n-1}(Av_0) = \lambda A^{n-1} v_0 = \lambda^2 A^{n-2} v_0 \qquad \ldots = \lambda^n v_0.$$

It is **much easier** to compute $v_n = \lambda^{10} v_0$.

Example

$$A = \begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \qquad v_0 = \begin{pmatrix} 16 \\ 4 \\ 1 \end{pmatrix} \qquad Av_0 = 2v_0.$$

Eigenvectors and Eigenvalues

This is the most important definition in the course.

Definition

Let A be an $n \times n$ matrix.

1. An **eigenvector** of A is a *nonzero vector* v in $\mathbf{R}^n$ such that $Av = \lambda v$, for some λ in $\mathbf{R}$.
2. We say that the *number* λ is the **eigenvalue for** v, and v is an **eigenvector for** λ.

Notes:

- Eigenvalues and eigenvectors are only for square matrices.
- Eigenvectors are by definition nonzero. Eigenvalues may be equal to zero.

Verifying Eigenvectors

Example

$$A = \begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \qquad v = \begin{pmatrix} 16 \\ 4 \\ 1 \end{pmatrix}$$

Multiply:

$$Av =$$

Example

$$A = \begin{pmatrix} 2 & 2 \\ -4 & 8 \end{pmatrix} \qquad v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Multiply:

$$Av =$$

Poll

Verifying Eigenvalues

Question: Is $\lambda = 3$ an eigenvalue of $A = \begin{pmatrix} 2 & -4 \\ -1 & -1 \end{pmatrix}$?

In other words, does

$$\left.\begin{aligned} Av &= 3v \\ Av - 3v &= 0 \\ (A - 3I)v &= 0 \end{aligned}\right\} \text{have a nontrivial solution?}$$

We know how to answer that!

Eigenspaces

Definition

Let A be an $n \times n$ matrix and let λ be an eigenvalue of A. The **λ-eigenspace** of A is the set of all *eigenvectors of A with eigenvalue λ, plus the zero* vector:

$$\begin{aligned}\lambda\text{-eigenspace} &= \{v \text{ in } \mathbf{R}^n \mid Av = \lambda v\} \\ &= \{v \text{ in } \mathbf{R}^n \mid (A - \lambda I)v = 0\} \\ &= \mathrm{Nul}(A - \lambda I).\end{aligned}$$

The λ-eigenspace is a *subspace* of $\mathbf{R}^n$. How to find a basis? Parametric vector form!

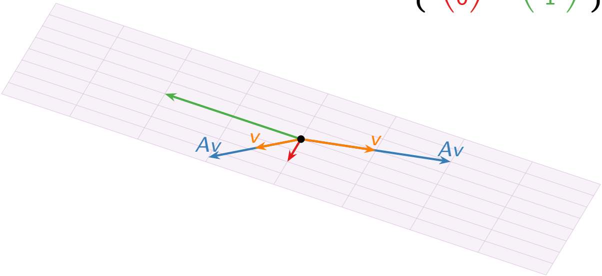
Find a basis for the 2-eigenspace of

λ

$$A = \begin{pmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{pmatrix}.$$

This is how eigenvalues and eigenvectors make matrices easier to understand.

What does this 2-eigenspace look like? A basis is $\left\{ \begin{pmatrix} \frac{1}{2} \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} \right\}$.



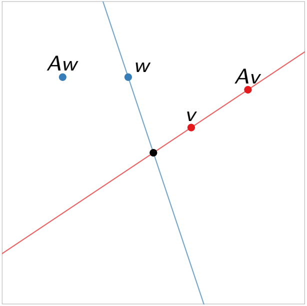
For any v in the 2-eigenspace, $Av = 2v$ by definition.
This means, on its 2-eigenspace, A acts by *scaling by* 2.

Geometrically

Eigenvectors

An eigenvector of a matrix A is *a nonzero vector v* such that:

- Av is a multiple of v, which means
- *Av is on the same line* as v.

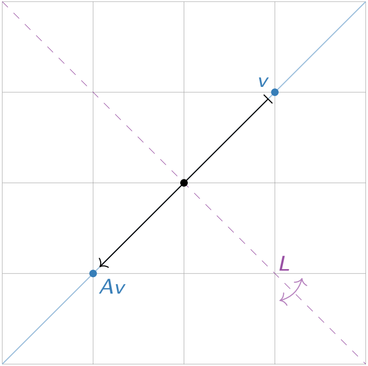


v is an eigenvector

w is not an eigenvector

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*



Which vectors don't move off their line

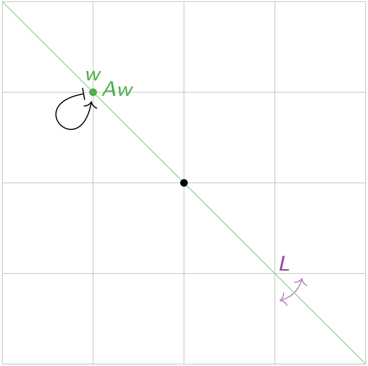
v is an eigenvector with eigenvalue -1.

Eigenspaces

Geometry; example

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*



Which vectors don't move off their line

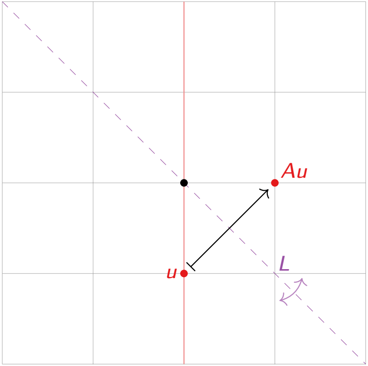
w is an eigenvector with eigenvalue 1.

Eigenspaces

Geometry; example

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*

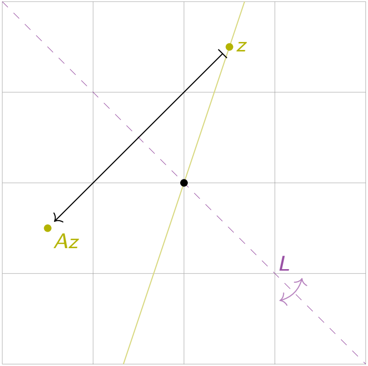


Which vectors don't move off their line

u is *not* an eigenvector.

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*



Which vectors don't move off their line

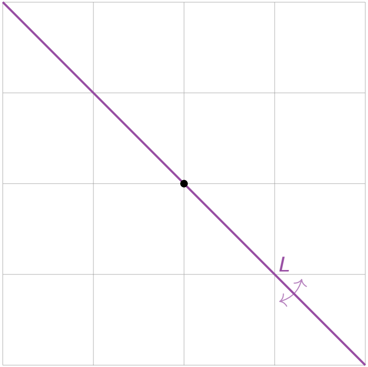
Neither is z.

Eigenspaces

Geometry; example

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*

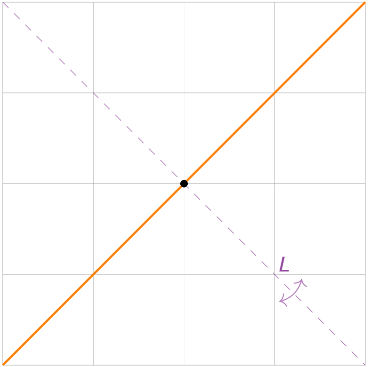


Which vectors don't move off their line

The 1-eigenspace is L
(all the vectors x where $Ax = x$).

Let $T: \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: Eigenvalues and eigenspaces of A? *No computations!*



Which vectors don't move off their line

The (-1)-eigenspace is the line $y = x$
(all the vectors x where $Ax = -x$).

Let A be an $n \times n$ matrix and let λ be a number.

1. λ is an **eigenvalue of A**
   if and only if $(A - \lambda I)x = 0$ *has a nontrivial solution*,
   if and only if $\mathrm{Nul}(A - \lambda I) \neq \{0\}$.
2. Finding a basis for the **λ-eigenspace of A**
   means finding a basis for $\mathrm{Nul}(A - \lambda I)$ as usual, through
   the *general solution to $(A - \lambda I)x = 0$* (parametric vector form).
3. The **eigenvectors** with eigenvalue λ are
   the nonzero elements of $\mathrm{Nul}(A - \lambda I)$
   that is, the *nontrivial solutions* to $(A - \lambda I)x = 0$.

Some facts you can work out yourself

Fact 1

A is **invertible** if and only if 0 *is not an eigenvalue* of A.

Fact 2

If $v_1, v_2, \ldots, v_k$ are eigenvectors of A with **distinct eigenvalues** $\lambda_1, \ldots, \lambda_k$, then $\{v_1, v_2, \ldots, v_k\}$ is *linearly independent*.

Consequence of Fact 2

An $n \times n$ matrix has **at most** n distinct eigenvalues.

The Eigenvalues of a Triangular Matrix are the Diagonal Entries

- If we **know λ is eigenvalue**: easy to find eigenvectors (*row reduction*).
- And to **find all eigenvalues**? Will need to *compute a determinant*.

Theorem

The **eigenvalues** of a triangular matrix are the *diagonal entries*.

Example

Find all eigenvalues of $A = \begin{pmatrix} 3 & 4 & 1 \\ 0 & -1 & -2 \\ 0 & 0 & 3 \end{pmatrix}$.